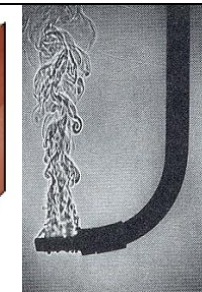
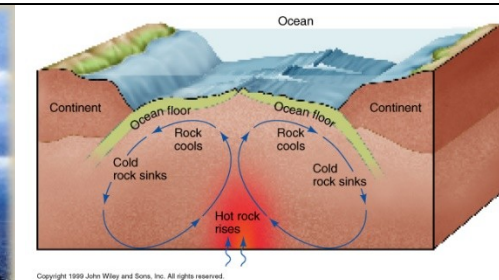
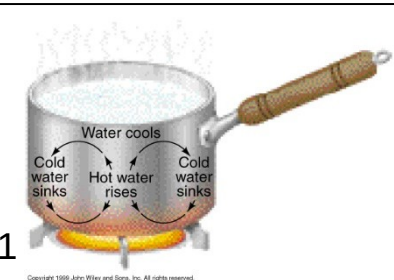


September 2002 06:19 MIST NOVA 15

Introduction to Ordinary Differential Equations



Ordinary Differential Equations

- Where do ODEs arise?
- Notation and Definitions
- Solution methods for 1st order ODEs





Where do ODE's arise

- All branches of Engineering
- Economics
- Biology and Medicine
- Chemistry, Physics etc

Anytime you wish to find out how something changes with time (and sometimes space)



Example – Newton’s Law of Cooling

- This is a model of how the temperature of an object changes as it loses heat to the surrounding atmosphere:

Temperature of the object: T_{Obj} Room Temperature: T_{Room}

Newton’s laws states: “*The rate of change in the temperature of an object is proportional to the difference in temperature between the object and the room temperature*”

Form
ODE

$$\frac{dT_{Obj}}{dt} = -\alpha(T_{Obj} - T_{Room})$$

Solve
ODE

$$T_{Obj} = T_{Room} + (T_{init} - T_{Room})e^{-\alpha t}$$

Where T_{init} is the initial temperature of the object.




Notation and Definitions

- Order
- Linearity
- Homogeneity
- Initial Value/Boundary value problems



Order

- The order of a differential equation is just the order of highest derivative used.

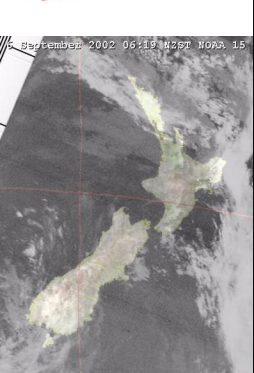
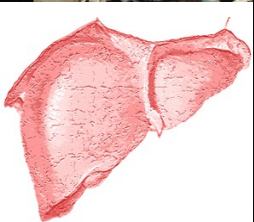
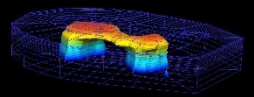

$$\frac{d^2 y}{dt^2} + \frac{dy}{dt} = 0 \quad \longrightarrow \quad 2^{\text{nd}} \text{ order}$$

$$\frac{dx}{dt} = x \frac{d^3 x}{dt^3} \quad \longrightarrow \quad 3^{\text{rd}} \text{ order}$$

Linearity

- The important issue is how the unknown y appears in the equation. A linear equation involves the dependent variable (y) and its derivatives by themselves. There must be no "unusual" nonlinear functions of y or its derivatives.
- A linear equation must have constant coefficients, or coefficients which depend on the independent variable (t). If y or its derivatives appear in the coefficient the equation is nonlinear.

Linearity - Examples



$$\frac{dy}{dt} + y = 0 \quad \text{is linear}$$

$$\frac{dx}{dt} + x^2 = 0 \quad \text{is non-linear}$$

$$\frac{dy}{dt} + t^2 = 0 \quad \text{is linear}$$

$$y \frac{dy}{dt} + t^2 = 0 \quad \text{is non-linear}$$

Linearity – Summary

Linear	Non-linear
$2y$	y^2 or $\sin(y)$
$\frac{dy}{dt}$	$y \frac{dy}{dt}$
$(2 + 3\sin t)y$	$(2 - 3y^2)y$
$t \frac{dy}{dt}$	$\left(\frac{dy}{dt}\right)^2$

Linearity – Special Property

If a linear homogeneous ODE has solutions:

$$y = f(t) \quad \text{and} \quad y = g(t)$$

then:

$$y = a \times f(t) + b \times g(t)$$

where a and b are constants,

is also a solution.



Linearity – Special Property

Example:

$$\frac{d^2 y}{dt^2} + y = 0 \text{ has solutions } y = \sin t \text{ and } y = \cos t$$

Check $\frac{d^2(\sin t)}{dt^2} + \sin t = -\sin t + \sin t = 0$

$$\frac{d^2(\cos t)}{dt^2} + \cos t = -\cos t + \cos t = 0$$

Therefore $y = \sin t + \cos t$ is also a solution:

$$\begin{aligned} \text{Check } & \frac{d^2(\sin t + \cos t)}{dt^2} + \sin t + \cos t \\ & = -\sin t - \cos t + \sin t + \cos t = 0 \end{aligned}$$

Homogeneity

- Put all the terms of the equation which involve the dependent variable on the LHS.
- **Homogeneous:** If there is nothing left on the RHS the equation is homogeneous (unforced or free)
- **Nonhomogeneous:** If there are terms involving t (or constants) - but not y - left on the RHS the equation is nonhomogeneous (forced)



Example



$$\frac{dv}{dt} = g$$

$$v(0) = v_0$$

- 1st order
- Linear
- Nonhomogeneous
- Initial value problem

$$\frac{d^2 M}{dx^2} = w$$

$$M(0) = 0$$

and

$$M(l) = 0$$

- 2nd order
- Linear
- Nonhomogeneous
- Boundary value problem

Example



$$\frac{d^2\theta}{dt^2} + \omega^2 \sin \theta = 0$$

$$\theta(0) = \theta_0, \quad \frac{d\theta}{dt}(0) = 0$$

- 2nd order
- Nonlinear
- Homogeneous
- Initial value problem

$$\frac{d^2\theta}{dt^2} + \omega^2 \theta = 0$$

$$\theta(0) = \theta_0, \quad \frac{d\theta}{dt}(0) = 0$$

- 2nd order
- Linear
- Homogeneous
- Initial value problem

Solution Methods - Direct Integration

- This method works for equations where the RHS does not depend on the unknown:
- The general form is:

$$\frac{dy}{dt} = f(t)$$

$$\frac{d^2 y}{dt^2} = f(t)$$

$$\vdots$$

$$\frac{d^n y}{dt^n} = f(t)$$

Direct Integration

- y is called the unknown or dependent variable;
- t is called the independent variable;
- “solving” means finding a formula for y as a function of t ;
- Mostly we use t for time as the independent variable but in some cases we use x for distance.



Direct Integration – Example

Find the velocity of a car that is accelerating from rest at 3 ms^{-2} :

$$\frac{dv}{dt} = a = 3$$
$$\Rightarrow v = 3t + c$$

If the car was initially at rest we have the condition:

$$v(0) = 0 \Rightarrow 0 = 3 \times 0 + c \Rightarrow c = 0$$
$$\Rightarrow v = 3t$$

Solution Methods - Separation

The separation method applies only to 1st order ODEs. It can be used if the RHS can be factored into a function of t multiplied by a function of y :

$$\frac{dy}{dt} = g(t)h(y)$$

Separation - General Idea

First Separate:

$$\frac{dy}{h(y)} = g(t)dt$$

Then integrate LHS with respect to y , RHS with respect to t .

$$\int \frac{dy}{h(y)} = \int g(t)dt + C$$



Separation - Example

$$\frac{dy}{dt} = y \sin(t)$$

Separate:

$$\frac{1}{y} dy = \sin(t) dt$$

Now integrate:

$$\int \frac{1}{y} dy = \int \sin(t) dt$$

$$\Rightarrow \ln(y) = -\cos(t) + c$$

$$\Rightarrow y = e^{-\cos(t)+c}$$

$$\Rightarrow y = Ae^{-\cos(t)}$$